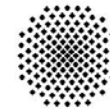


The Leading Engine for Innovation and Entrepreneurship in Sustainable Energy

AFOSP: Alternative Floating Platform Designs for Offshore Wind Towers using Low Cost Materials



UNIVERSITAT POLITÈCNICA
DE CATALUNYA
BARCELONATECH



Universität
Stuttgart

gasNatural
fenosa 

1.- Project overview

1.1 Why a floating platform?

1.2 Goal of the project

1.3 Project Consortium and Tasks Allocation

1.4 Main results

2.- Technical approach

2.1 Why concrete

2.2 Design process

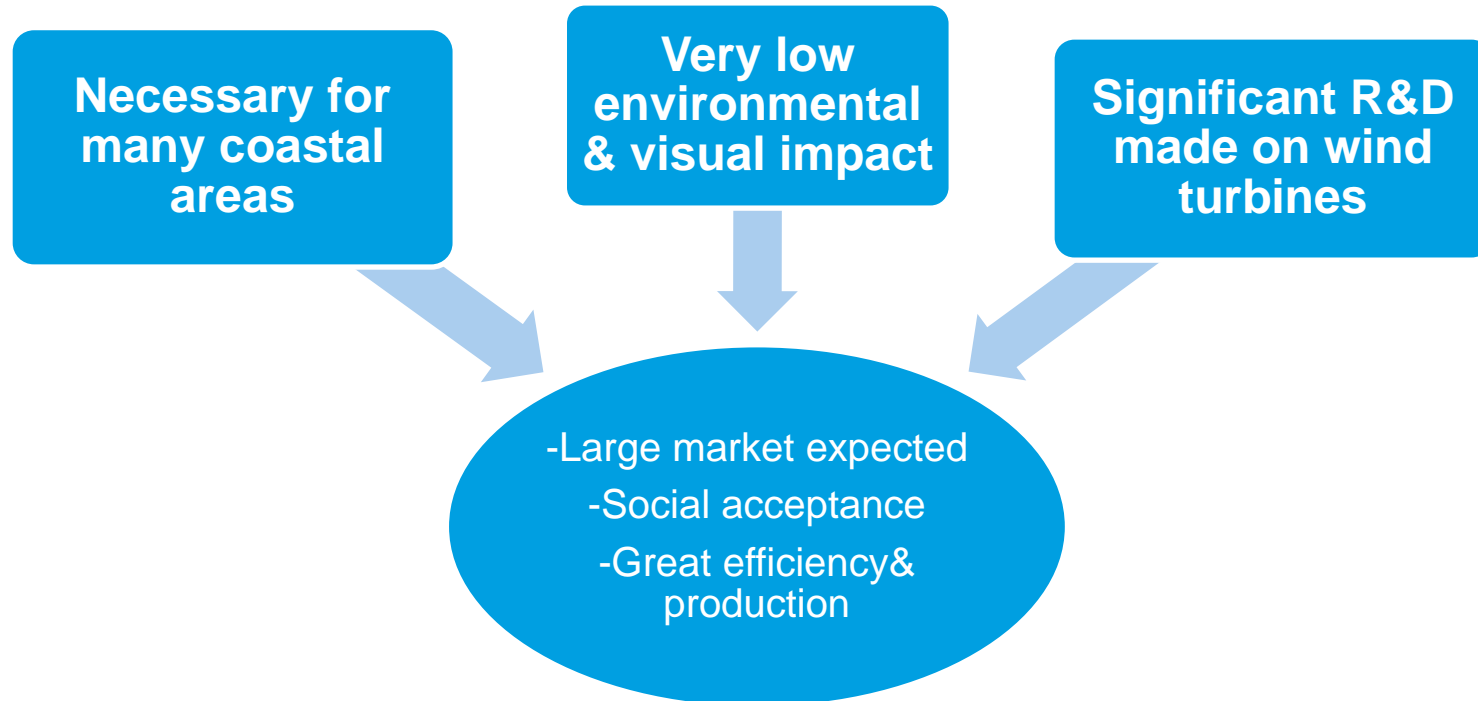
2.3 Verification: Experiments & Simulation

2.4 Construction & Installation

3.- Conclusions

4.- Q&A

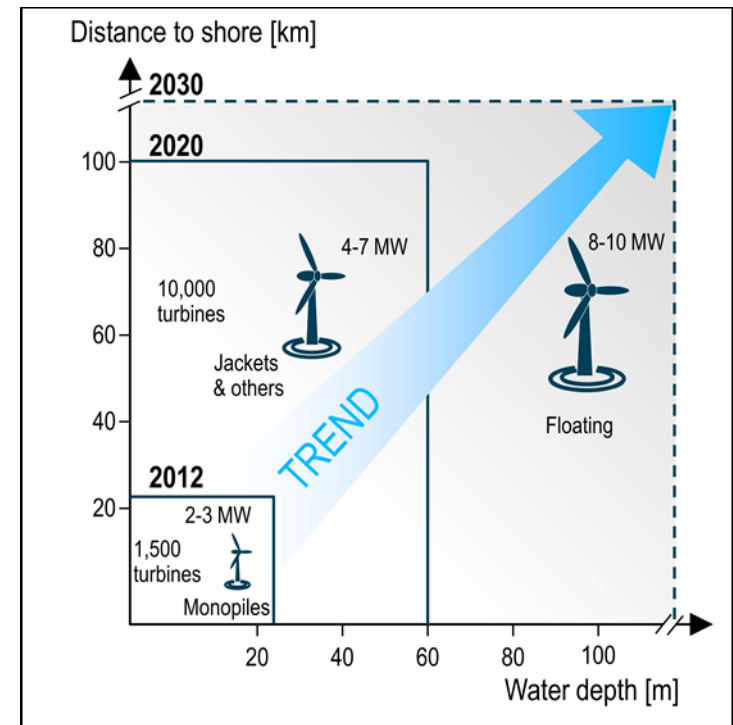
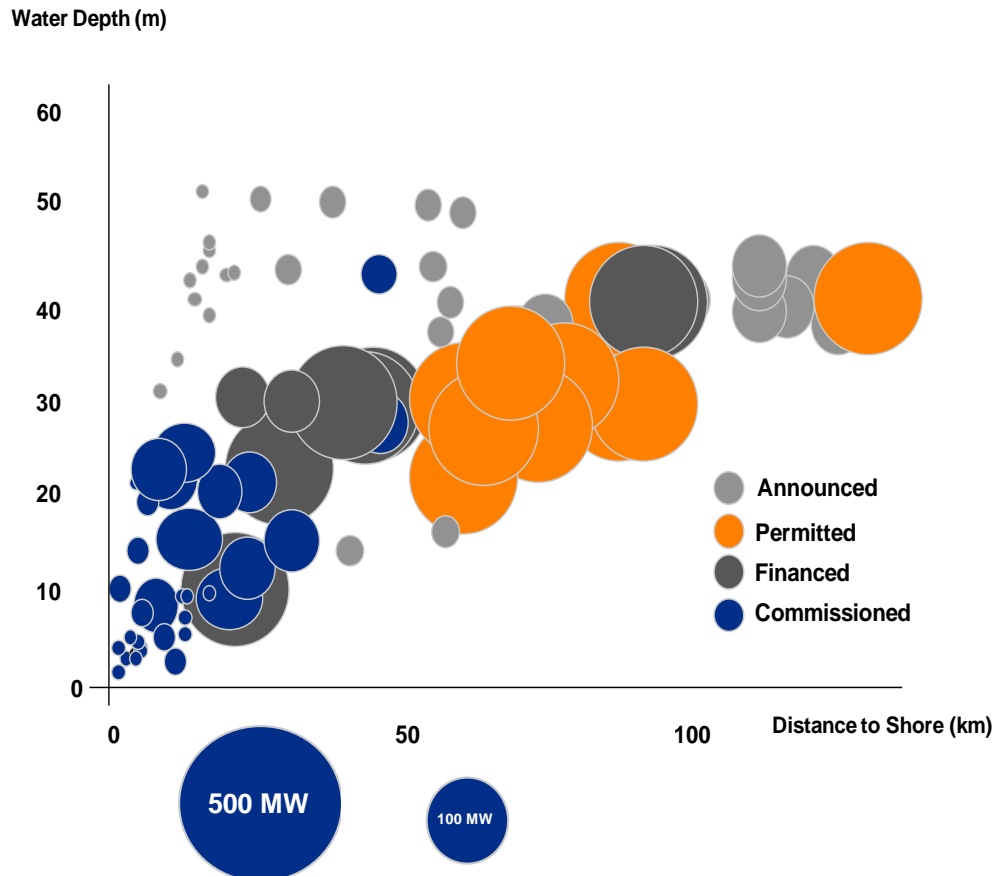
Floating offshore wind turbine support structure, WHY?



Importance to bring new low-cost prototypes to industry

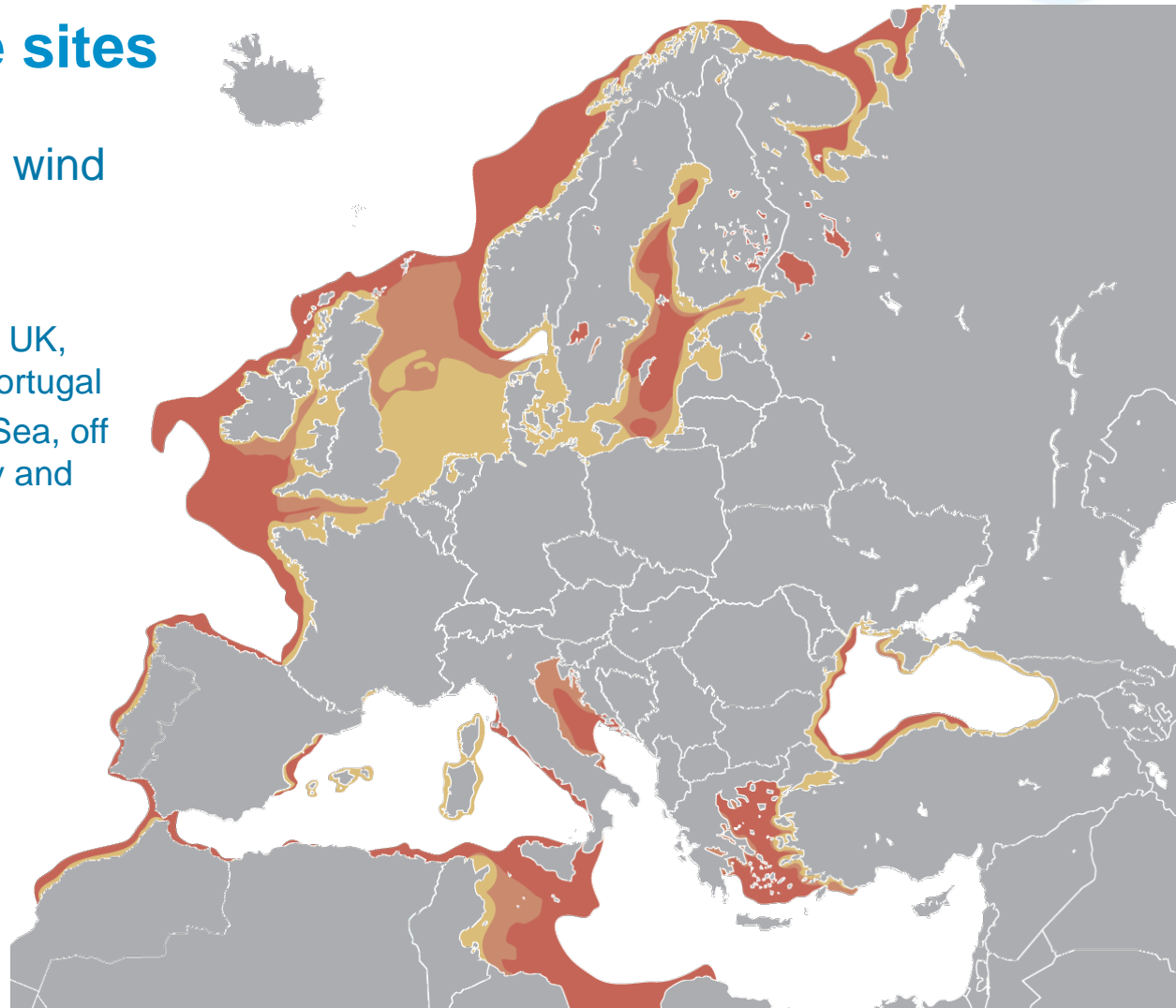
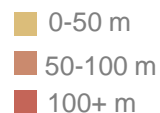
Offshore Deep Water Market Overview

Projects Status 2001 - 2015



Potential: Suitable sites

- Hotspots for floating wind developments:
- **In Europe:**
 - Towards the Atlantic: UK, Ireland, Spain and Portugal
 - The Northern North Sea, off the coasts of Norway and the UK
- **The US**
- **Japan**



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Design and
construct a
scale
prototype
Alternative
material:
CONCRETE



Proof of
concept
design
**Laboratory
tests
Coupled
simulations**



Proved
design
floating
platform
↓↓
€ct/kWh

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Partners



- Industrial partner
- Engineering *know-how*
- *Project management*



- Advanced design tools
- Expertise in coupled integrated IEC DLC simulations



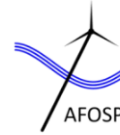
- Expertise in structural and maritime engineering
- Large wave channel for scale model testing



Governance



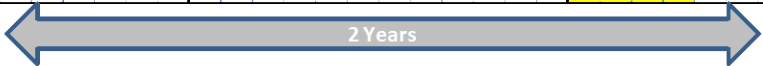
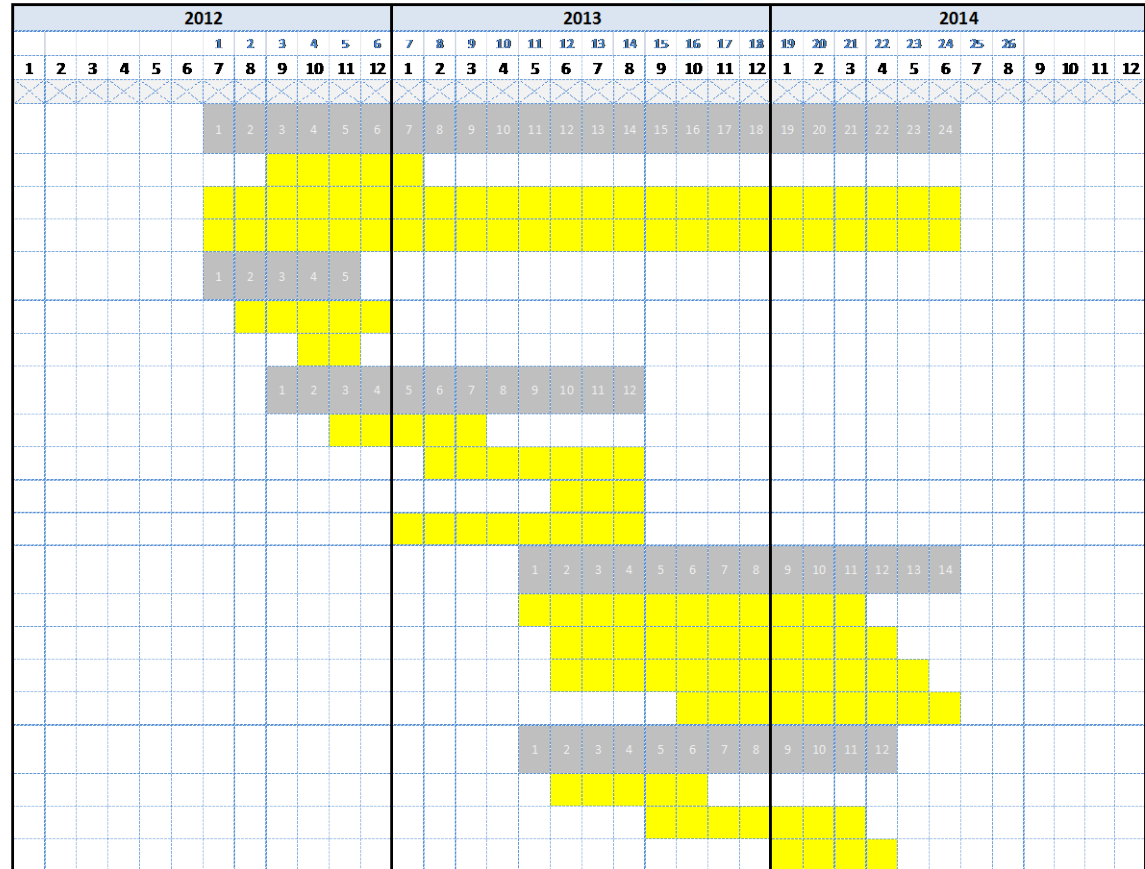
Planning



AFOSP: Project Schedule



- WP0** Project Management & Communication
- GNF**
 - T01- Market Analysis & Business Opportunities
 - T02- Education coordination
 - T03- Management, Dissemination & Reporting
- WP1** Analysis of the State of the Art
- USTUTT**
 - T11- State of Art Floating Platforms Concepts
 - T12- State of Art Application of cost effective
- WP2** Prototype Conceptual Design
- UPC**
 - T21- Study of Alternative Materials and Platform
 - T22- Predimensioning of prototype with Forces
 - T23- Definition of Mooring Lines and Anchors
 - T24- Definition of Control Strategy for a Floating
- WP3** Prototype Verification
- USTUTT**
 - T31- Model Setup
 - T32- Loads Analysis
 - T33- Feedback Loop
 - T34- Comparison of Scaled Test Results from WP4
- WP4** Scaled Testing
- UPC**
 - T41- Selection of the definitive Scale Model
 - T42- Laboratory Test on the Model
 - T43- Conclusion



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GNF

WP0

- Market Analysis
- LCOE analysis

USTUTT

WP1

- Analysis of state of the art

UPC

WP2

- Prototype pre-design



Patented design

USTUTT

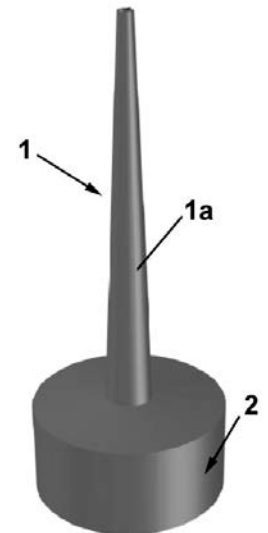
WP3

- Behavior of platform in coupled aero-hydro-servo-elastic simulations

UPC

WP4

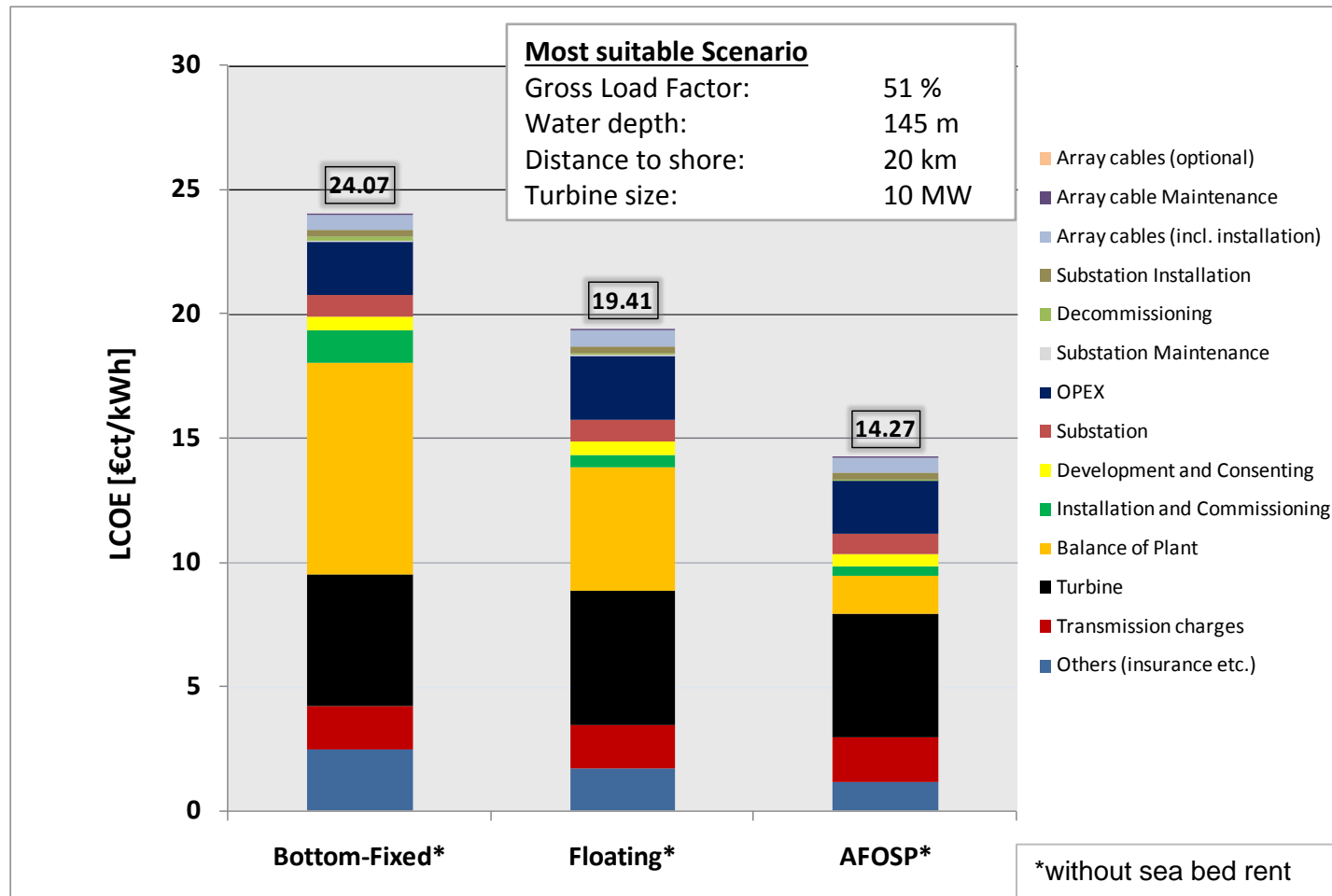
- Verification of scaled model prototype in laboratory channel



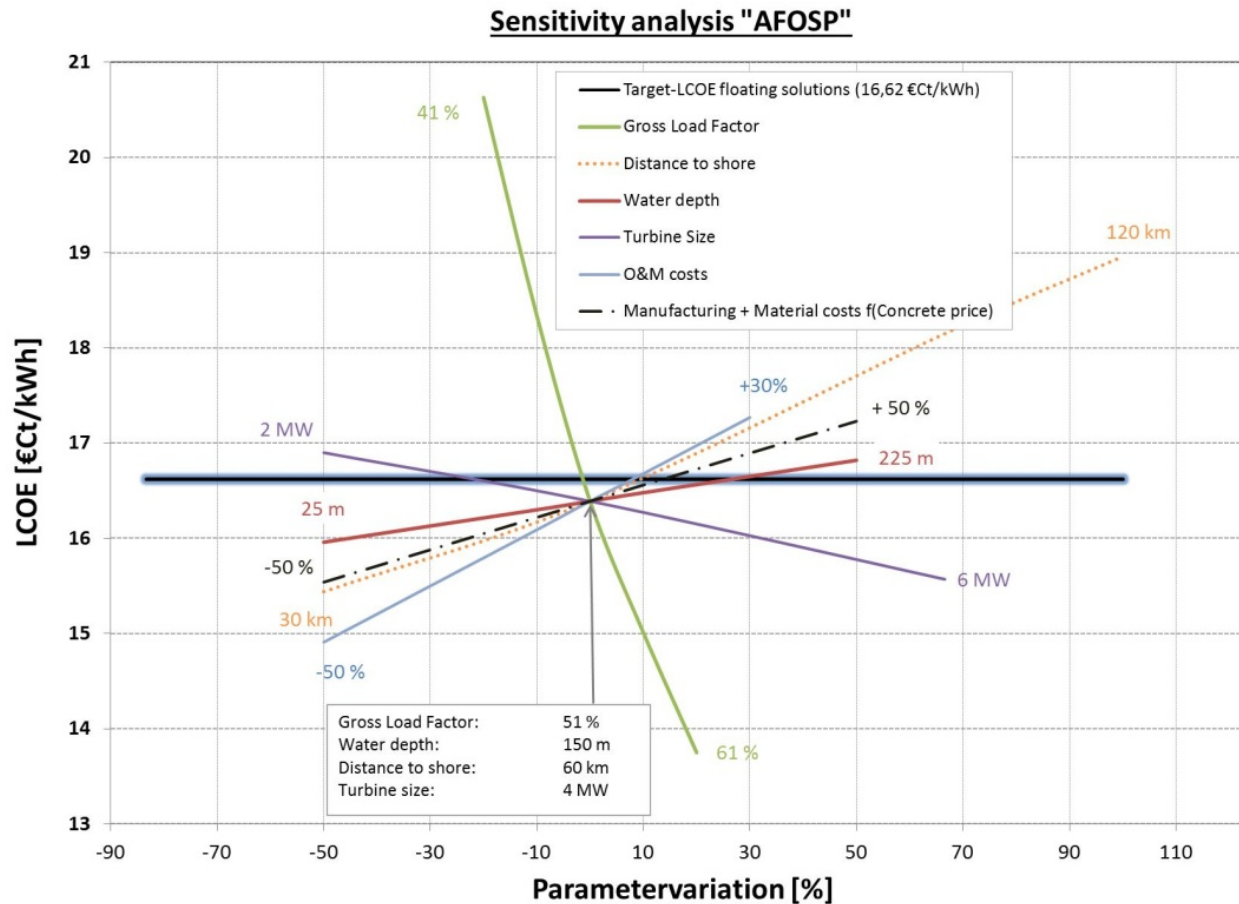
LCOE Analysis

The levelized cost of electricity (LCOE):

The cost of an electricity generation project over its lifetime in €/kWh, taking into account the present value of all the cost components (CAPEX & OPEX)



■ Sensitivity analysis



➔ Large dependency on the energy production and turbine size

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- Significant CAPEX costs reduction against other steel floating solutions
- Almost free of maintenance platform, reducing OPEX costs
- Higher resistance to fatigue loads and marine environment, lifetime protracted to 50 years
- Avoids joints between the tower and the floater, which are very sensible to fatigue loads
- Easy to build at large scale

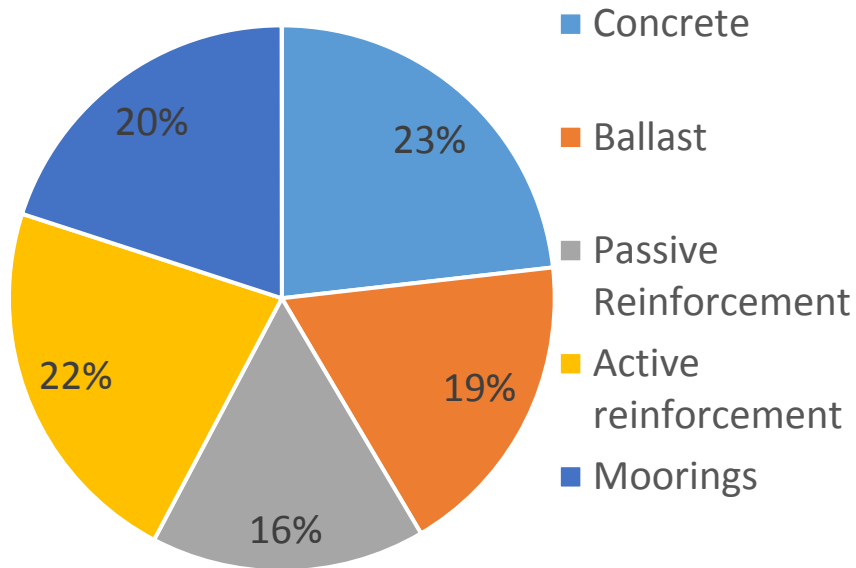
	Steel	Concrete
Diameter [m]	11.5	13
Water displ [m3]	1.297e+04	2.097E+04
Draft [m]	125	158
Structure mass [kg]	3.246E+06	1.219E+07
Ballast mass [kg]	9.698E+06	8.957E+06
RNA height (AMSL) [m]	87,6	87,6

Main design criteria

- Rotor weight 3.500 kN.
- Mean Thrust force 1.700 kN.
- Max. static tilt 5°.

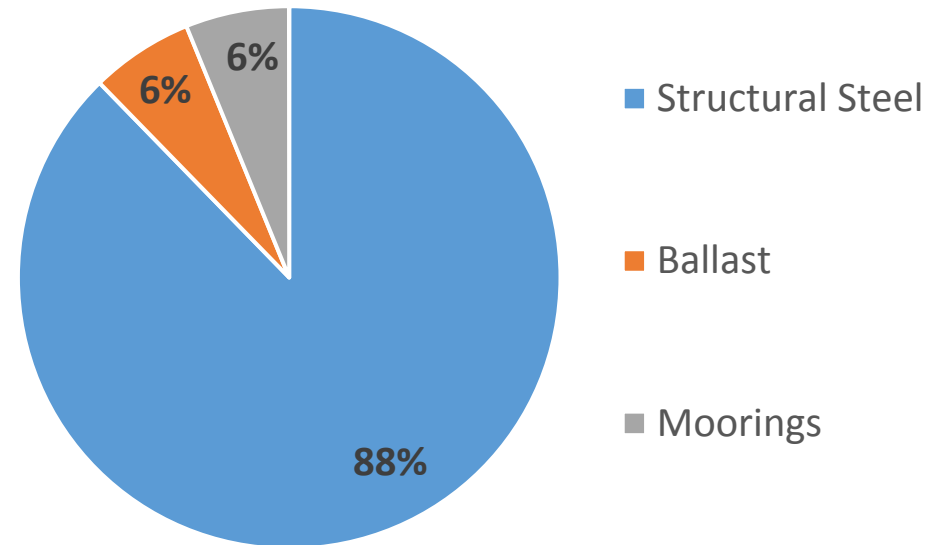
Unit / Platform Type	Steel SPAR	Concrete SPAR
Concrete	--	795,000.00 €
Structural Steel	9,738,000.00 €	--
Ballast	678,860.00 €	626,990.00 €
Passive Reinforcement	--	556,500.00 €
Active reinforcement	--	763,200.00 €
Mooring lines	685,314.00 €	685,314.00 €
TOTAL	11,102,174.00 €	3,427,004.00 €

Concrete SPAR costs



3,427,004.00 €

Steel SPAR



11,102,174.00 €

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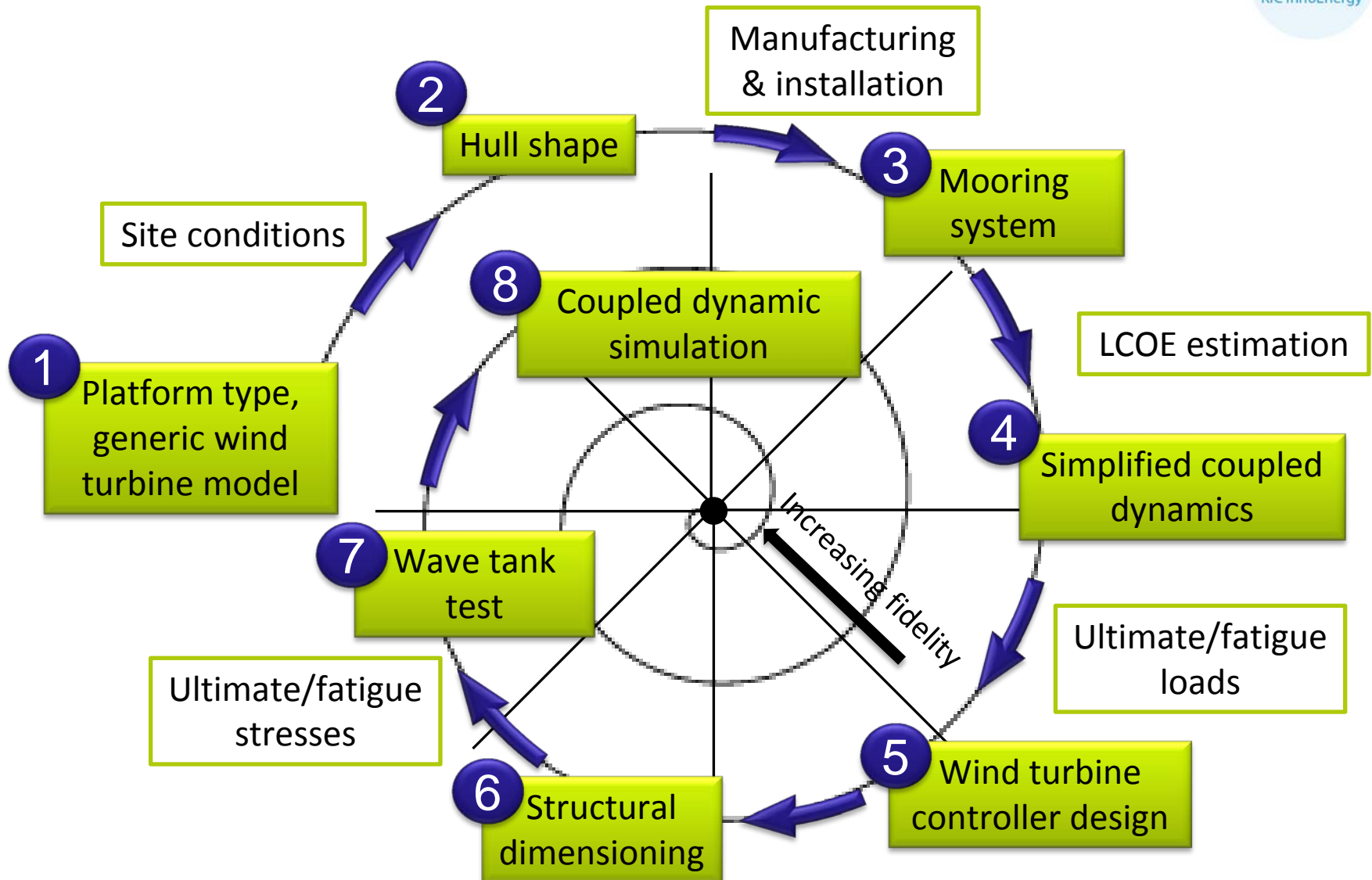
2.2 Design process

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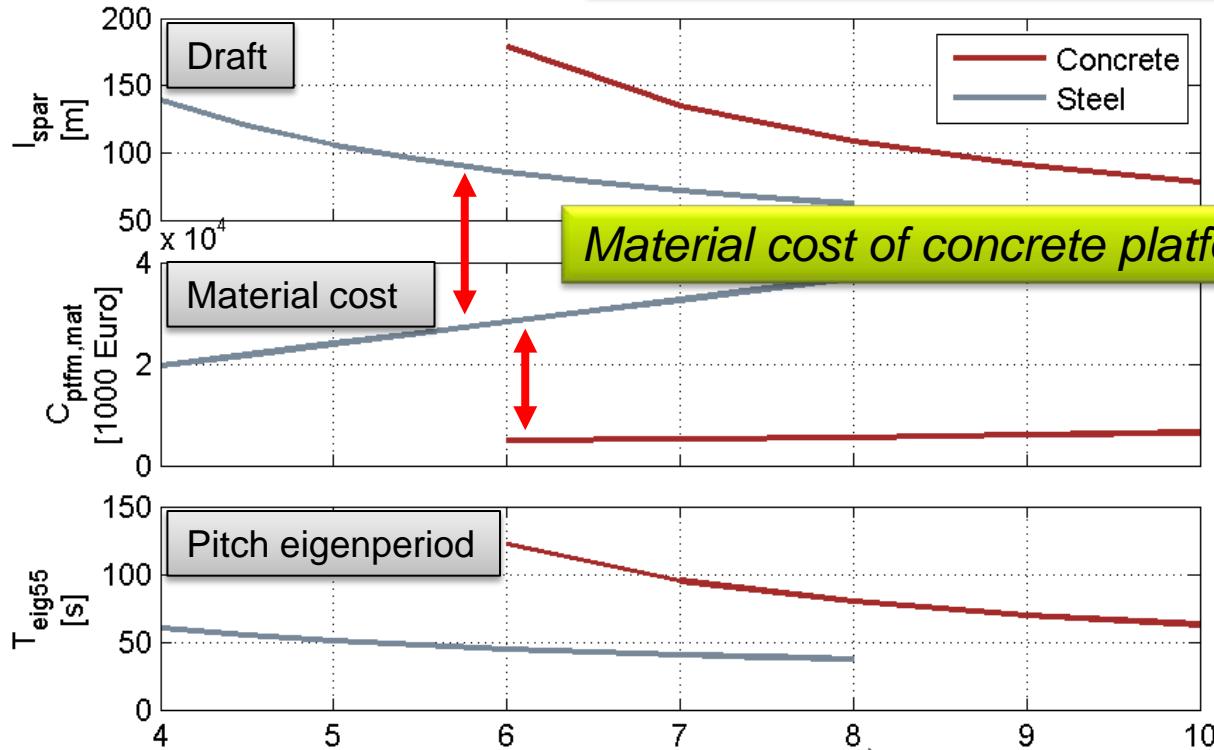
3.- Conclusions

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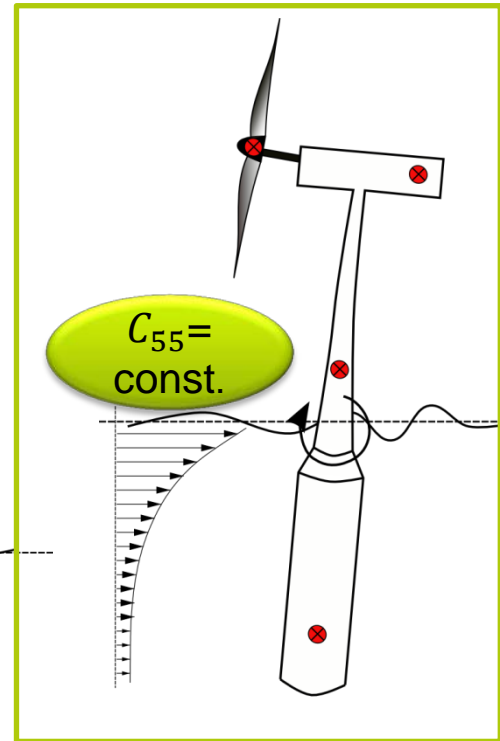
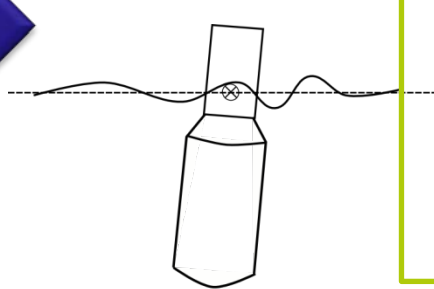
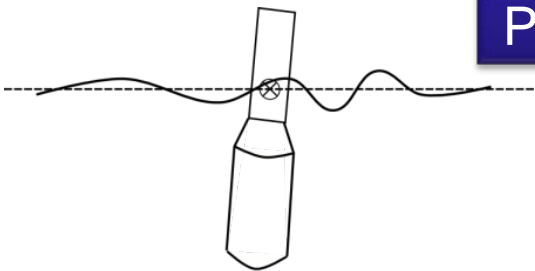
Spar hull design space

Cost increases with radius, draft decreases with radius

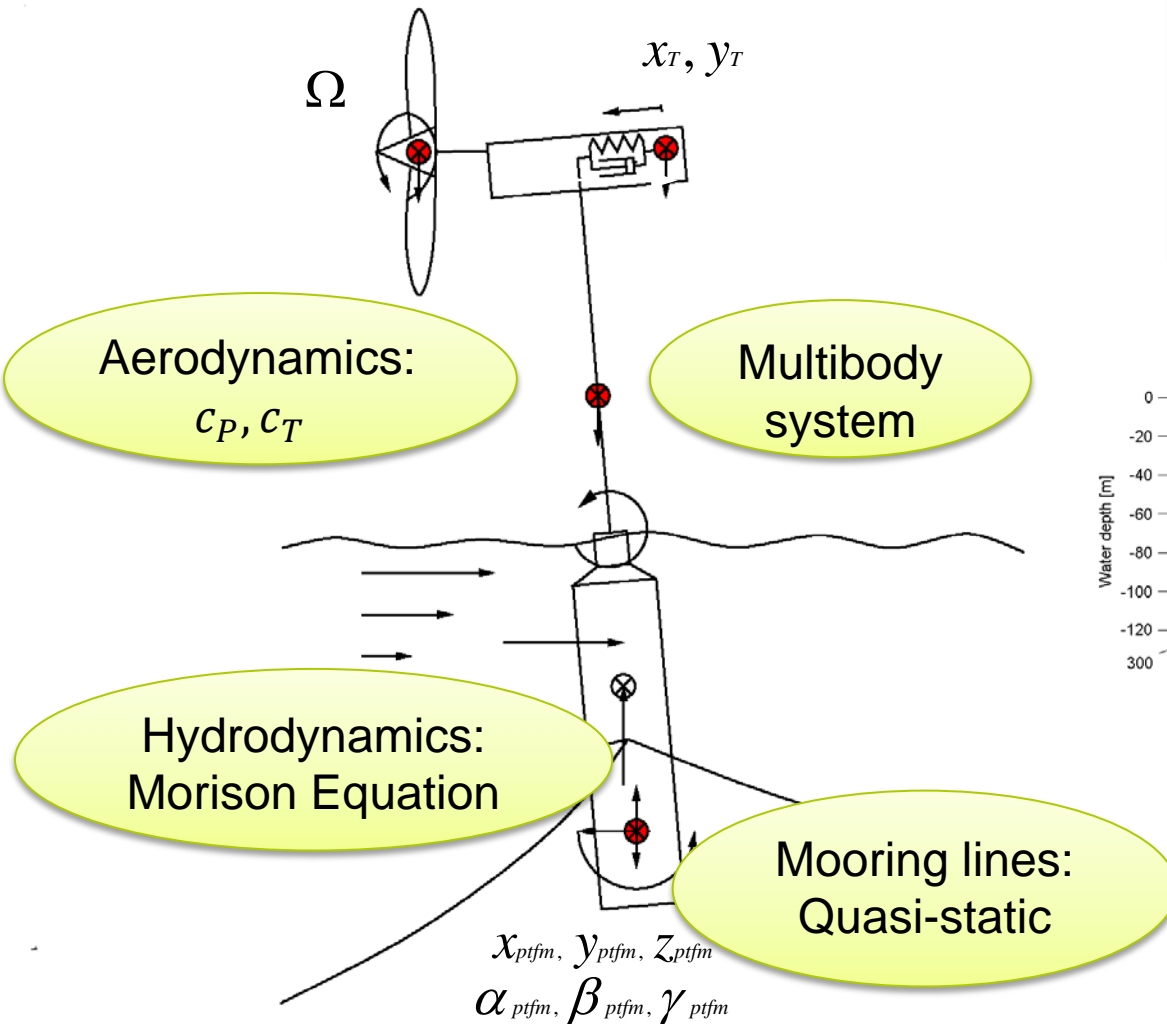


Material cost of concrete platform about 4 times smaller

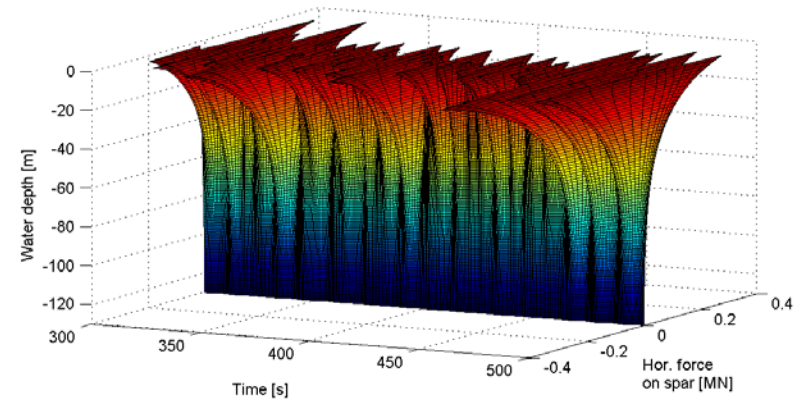
Platform radius [m]



Simplified dynamic simulation

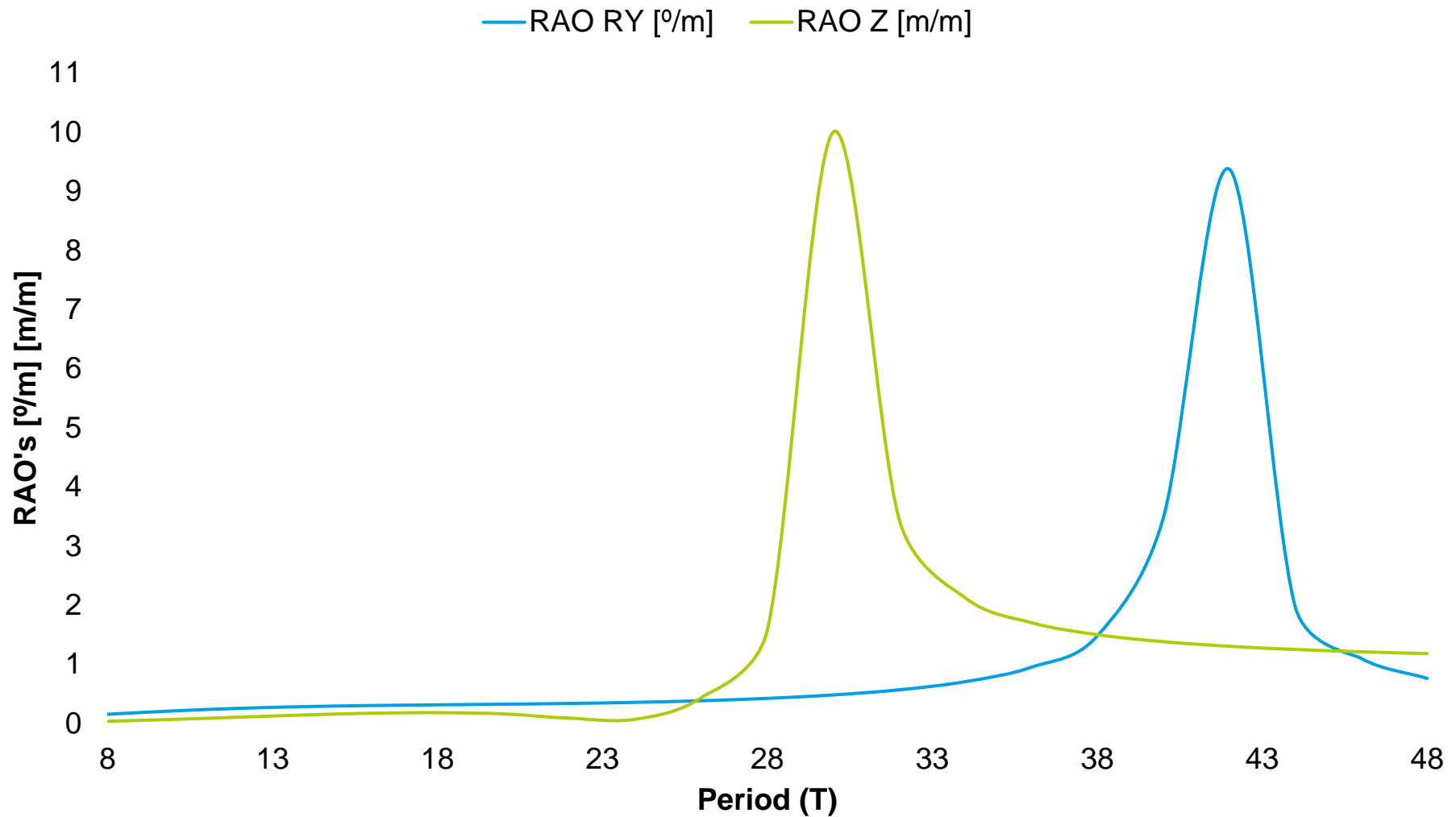


- 9 degrees of freedom
- Nonlinear
- Fully coupled
- Linearized for controller design

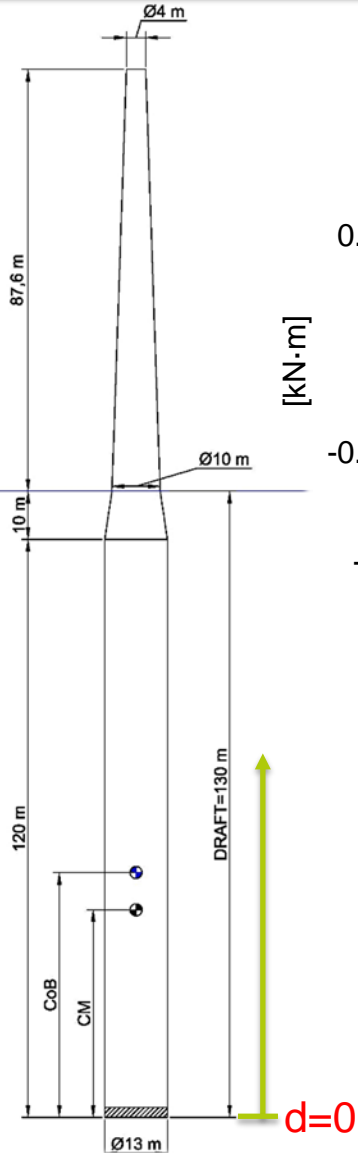


- Distributed external loads
- Ultimate/fatigue loads

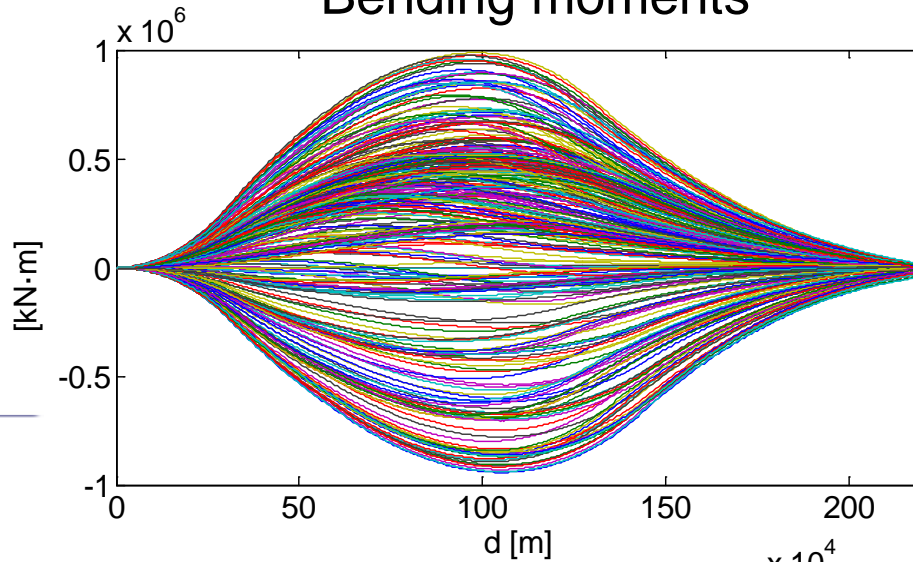
RAOs



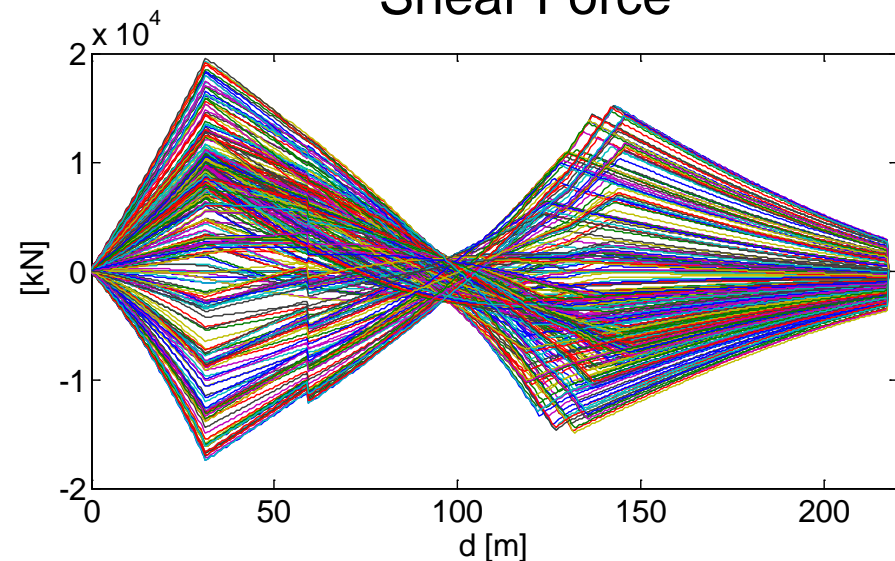
Structural analysis



Bending moments

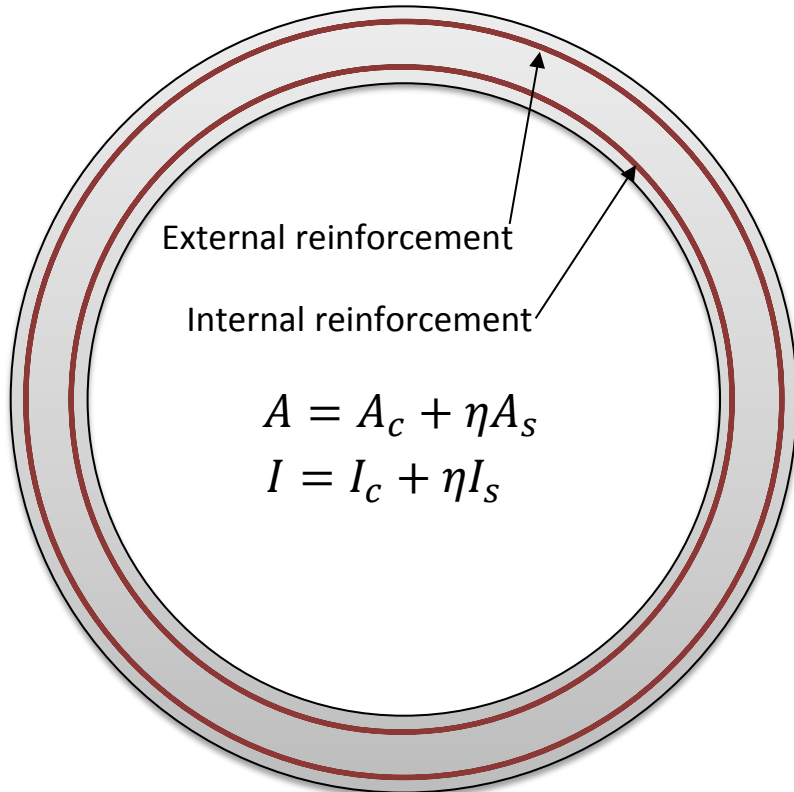


Shear Force



Limit State	SF
Ultimate Limit State	1.35
Fatigue Limit State	1.00

Structural analysis: ELU



EUROCODE-2

$$\sigma_{c,min} = \frac{N_k}{A} + \frac{\gamma_p P}{A} - \frac{M_k}{I} R_{ext}$$

$$0 \leq \sigma_c \leq 0.6 f_{ck}$$

MATERIAL	f_k	γ	f_d
Concrete	80 MPa	1.5	53.3 MPa
Prestressing steel	1,860 MPa	1.15	1617.4 MPa
Reinforcement steel	500 MPa	1.15	434.8 MPa

$$M_d \leq M_u$$

Section properties	Fp [kN]	Md [kN·m]	Mu [kN·m]
Floater	-359,652	1,055,000	1,167,000
Tower base	-394,740	843,100	912,000
Mid tower	-210,528	293,300	342,000

Structural analysis: Fatigue assessment

Fatigue Loadcase	Hs [m]	% Annual Time	Wind
50 year storm	13.8	0.02	Parked
1 year storm	10.8	0.08	Parked
1	2.5	68.8	≈14 m/s
2	3.0	19.5	≈14 m/s
3	5.0	10.7	≈14 m/s
4	7.0	0.8	Parked
5	9.0	0.2	Parked

DNV-OS-C502 LINEAR CUMULATIVE DAMAGE RULE

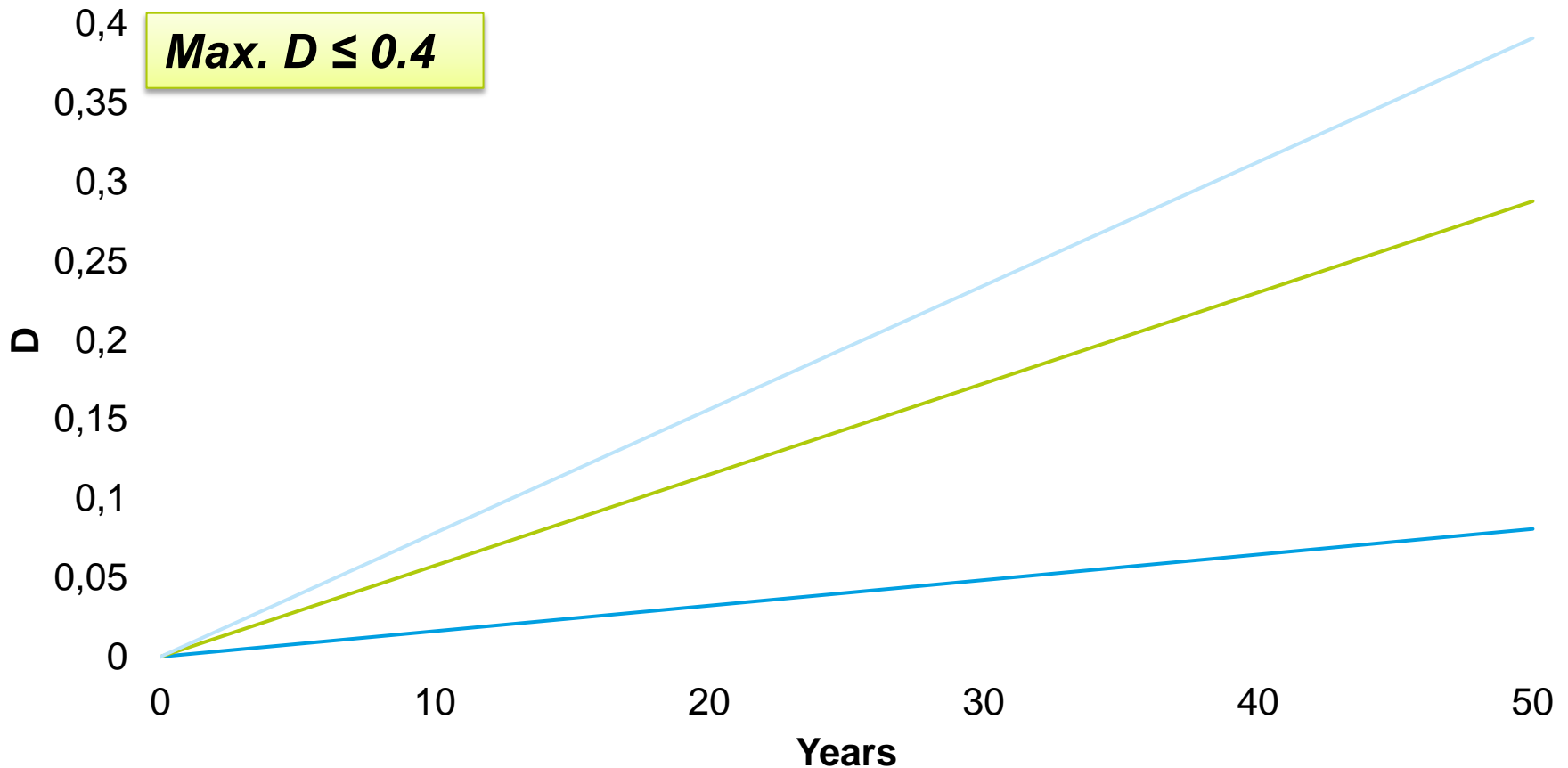
$$D = \sum_{i=1}^k \frac{n_i}{N_i} \leq \eta$$

$$\log_{10} N = C_1 \frac{\left(1 - \frac{\sigma_{\max}}{C_5 \cdot f_{rd}}\right)}{\left(1 - \frac{\sigma_{\min}}{C_5 \cdot f_{rd}}\right)}$$

Structural analysis: Fatigue assessment

50 years cumulated damage (D)

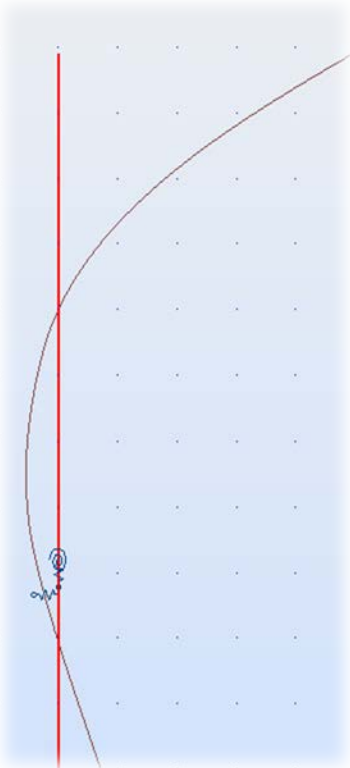
— Floater — Mid tower — Tower Base



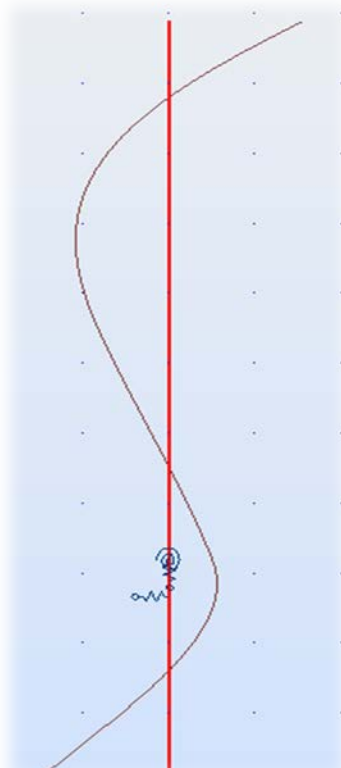
Structural analysis: Modal analysis

Modal shapes

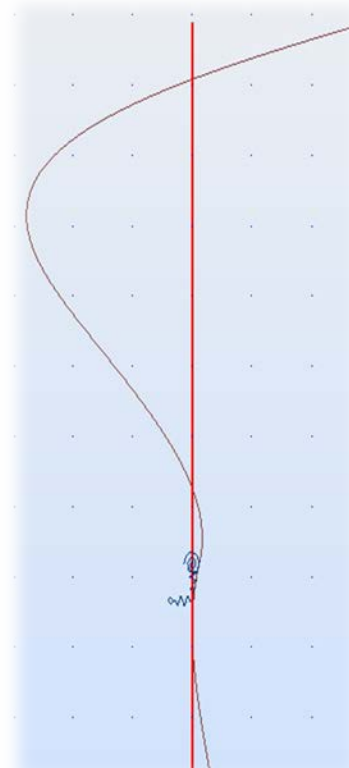
Mode 1



Mode 2



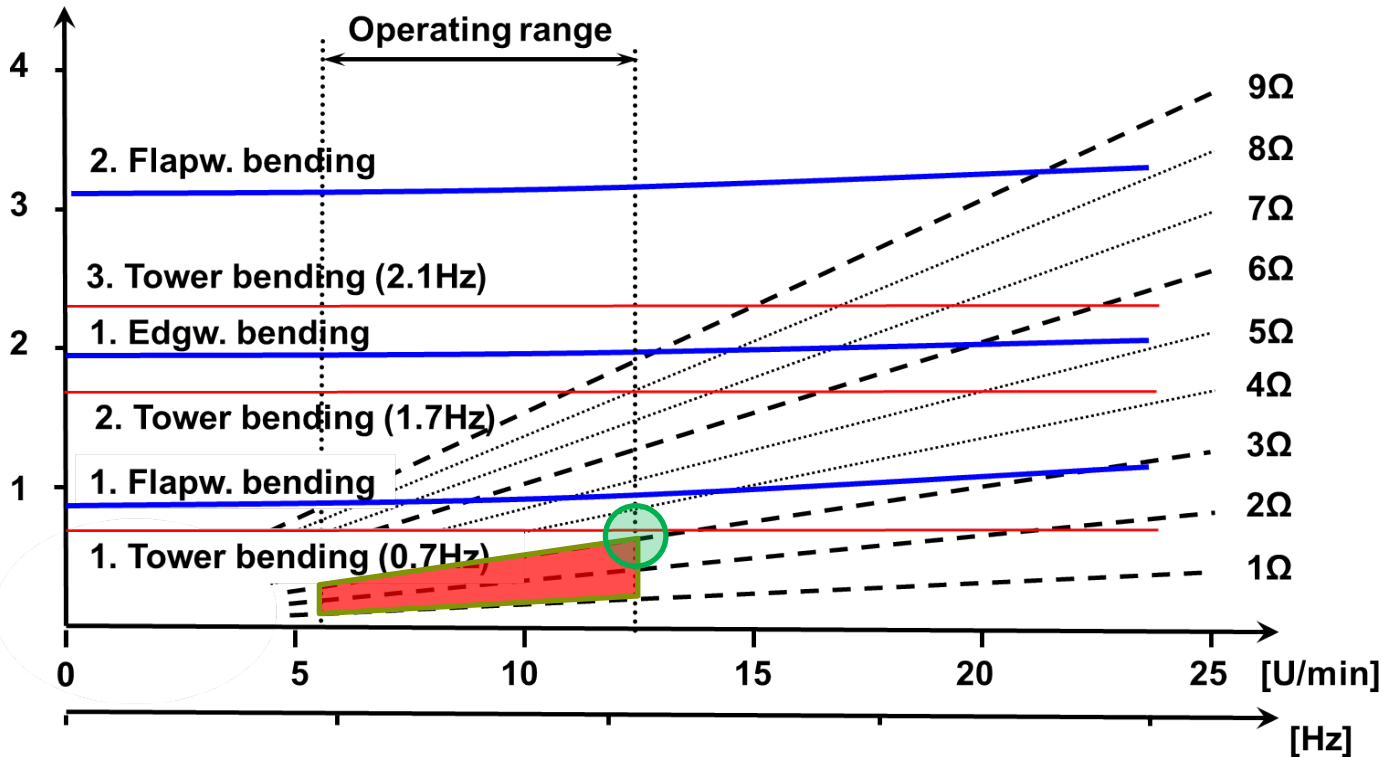
Mode 3



Mode	Freq [Hz]	Period [s]
1	0.711	1.406
2	1.696	0.590
3	2.134	0.469

Structural analysis: Modal analysis

NREL 5MW WT Campbell diagram



**1ST STRUCTURAL EIGENMODE
FALLS OUT OF THE RANGE
BETWEEN 1Ω & 3Ω**

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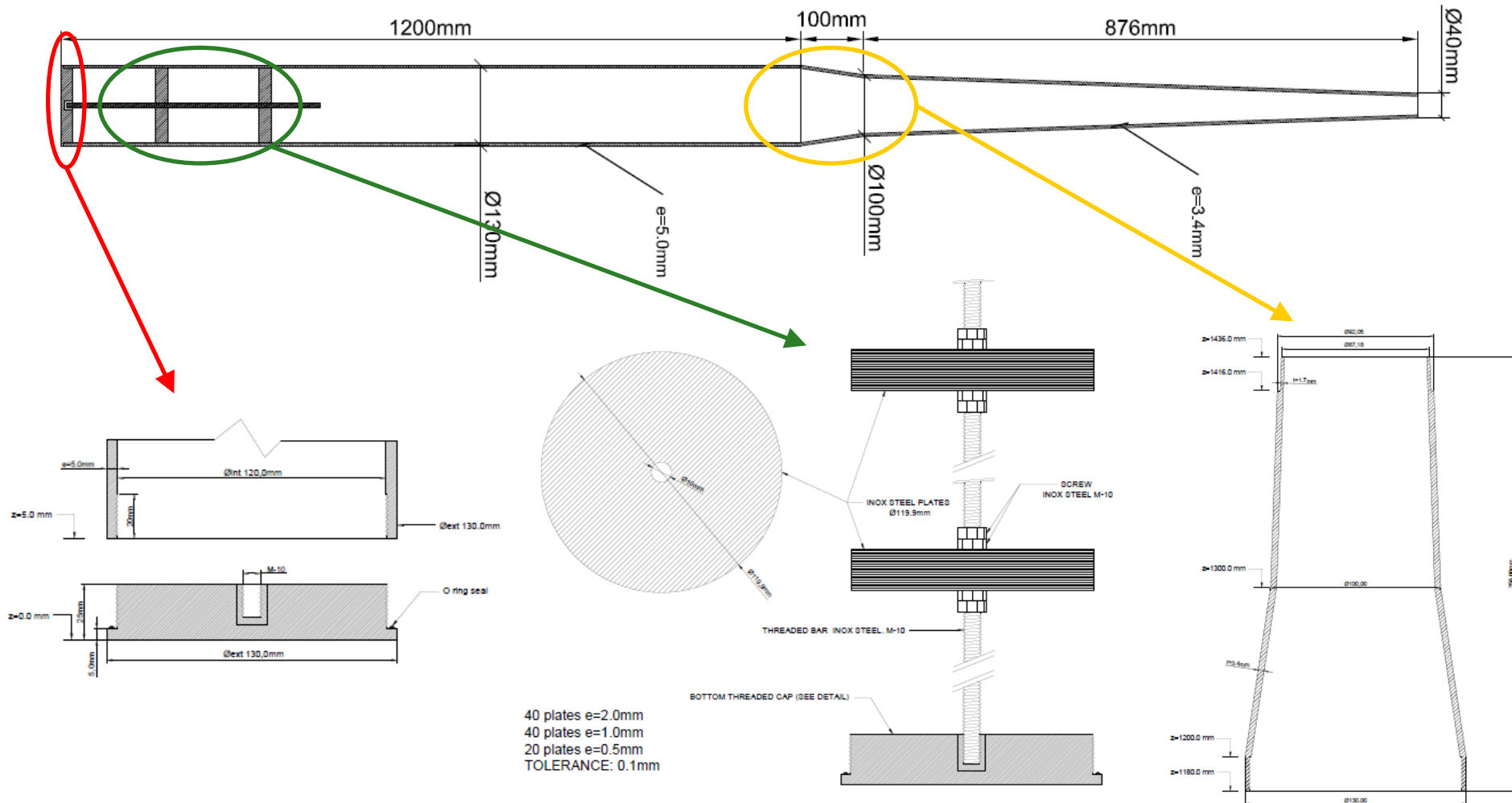
2.3 Verification: Experiments & Simulation

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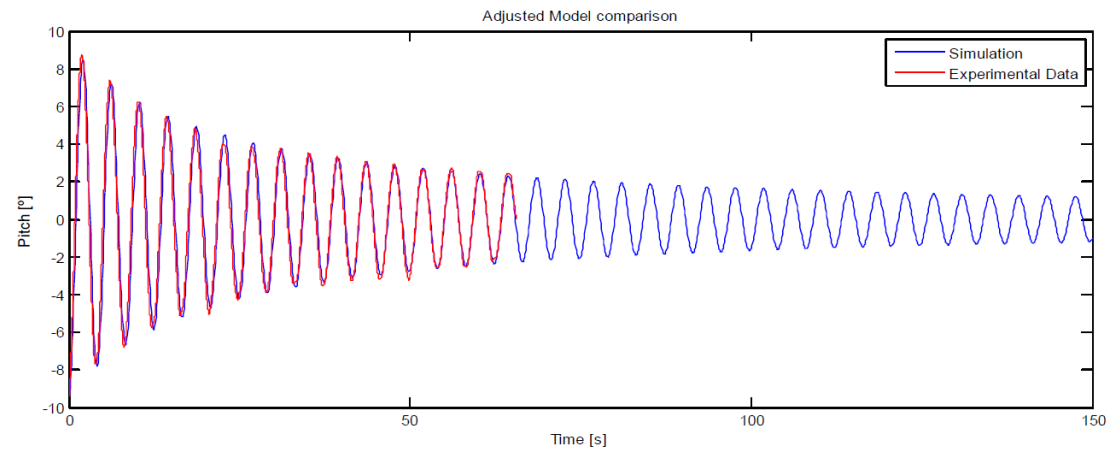
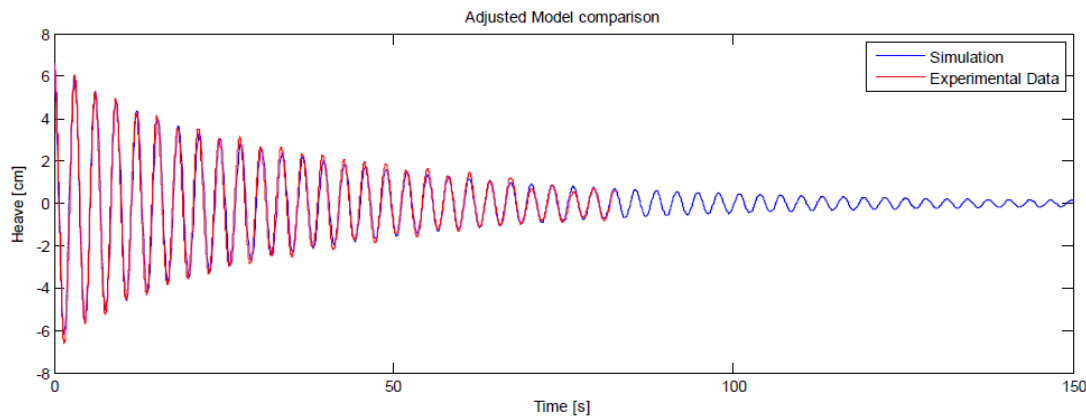
3.- Conclusions

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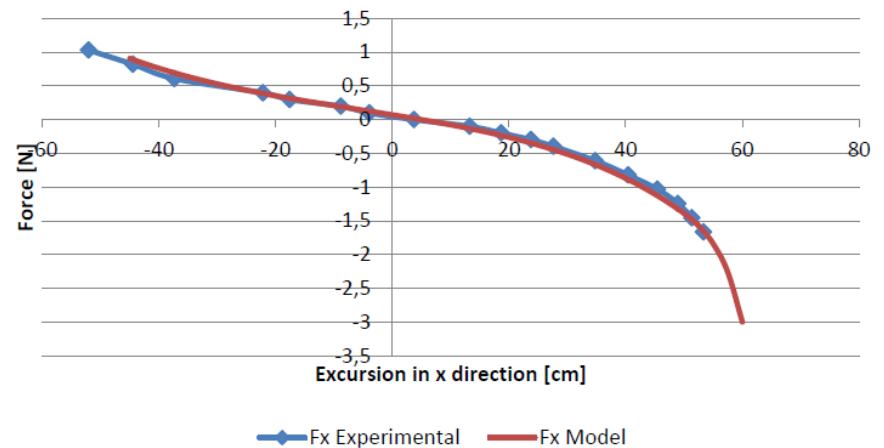
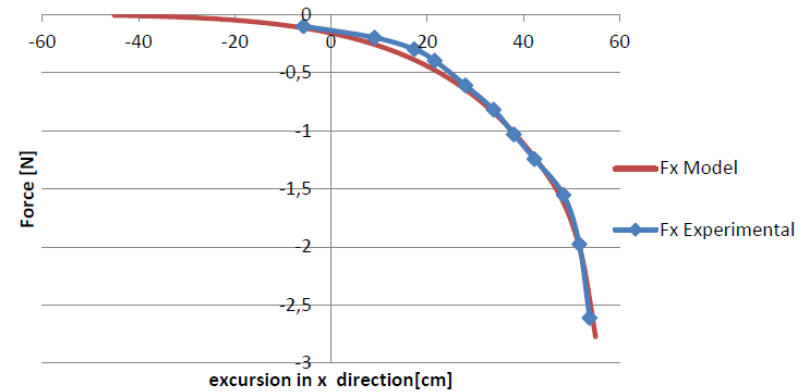
Froude similitude Scale 1:100



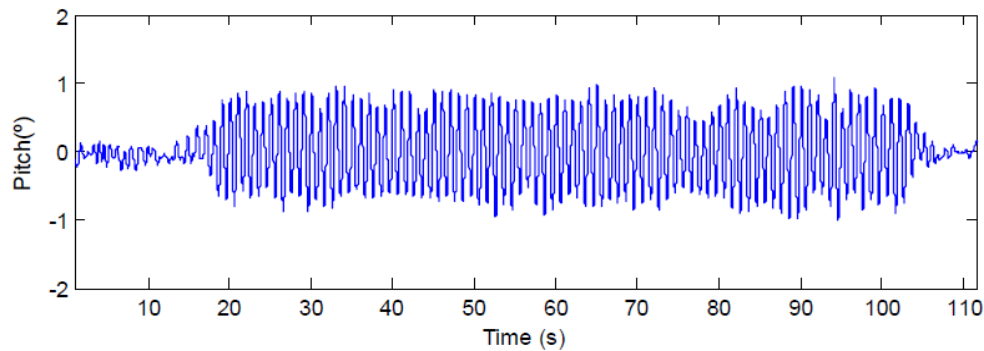
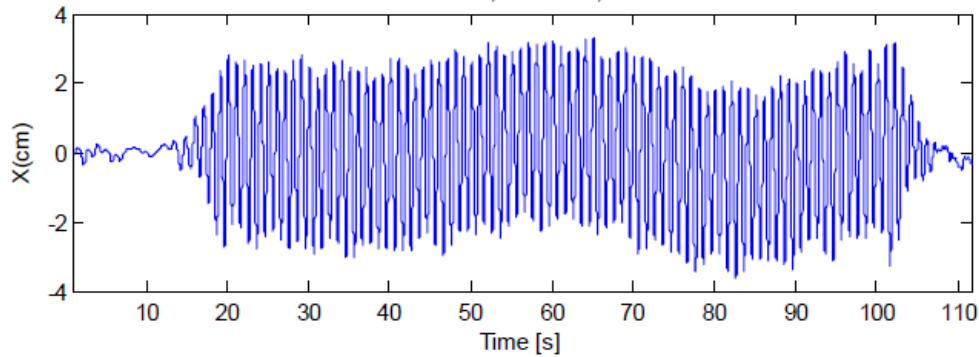
Scale testing: *Free decay tests*



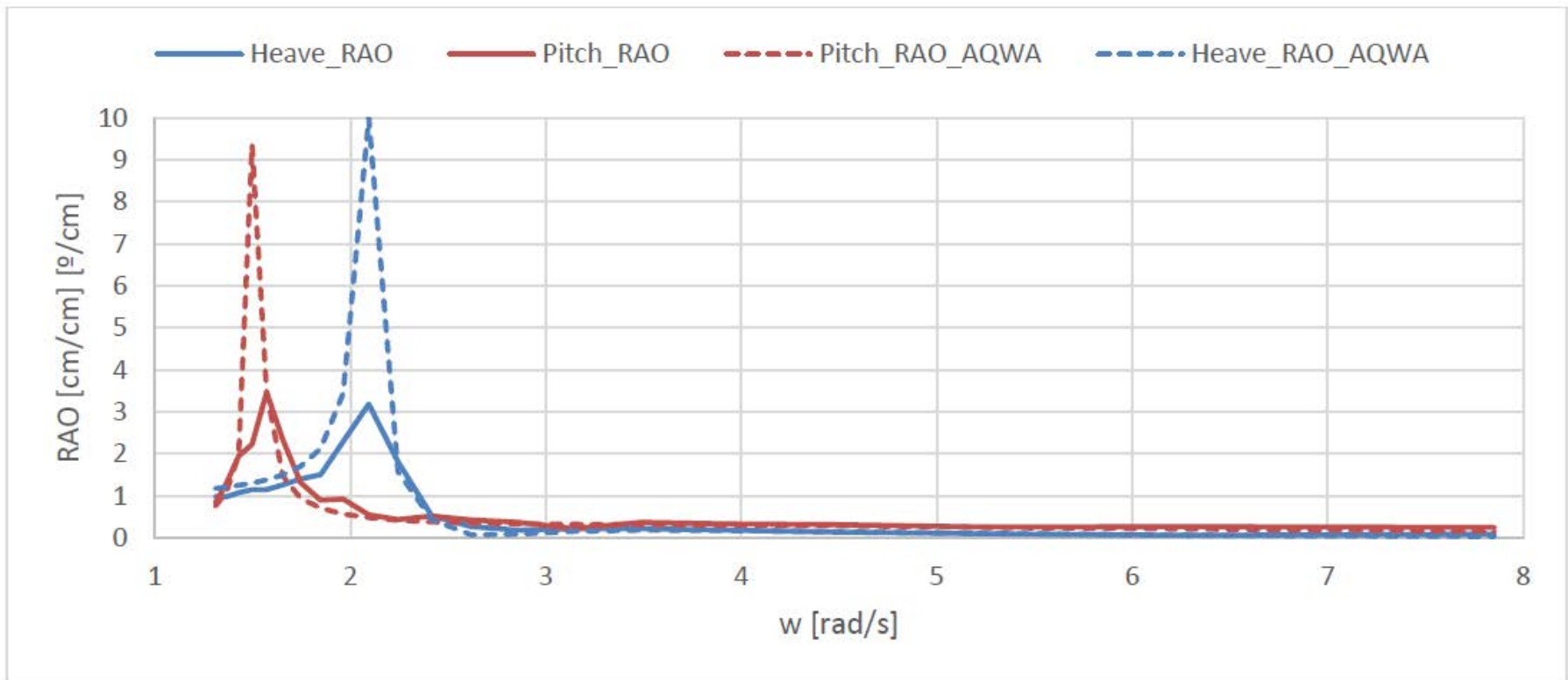
Scale testing: *Mooring system test*



Scale testing: *Experimental RAO's*

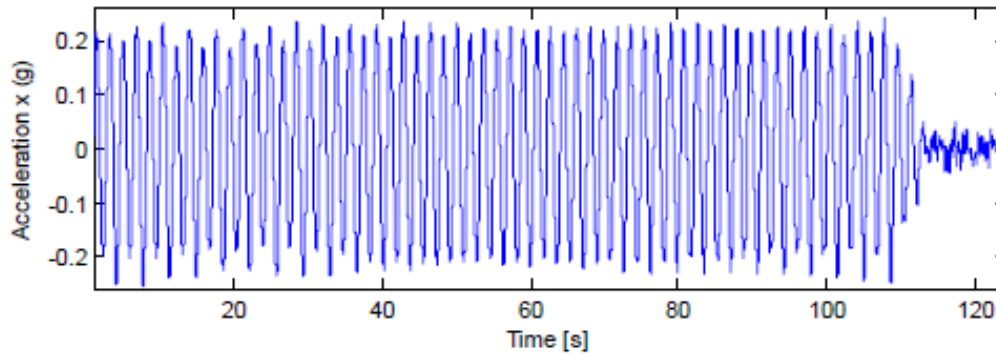


Scale testing: *Experimental RAO's*

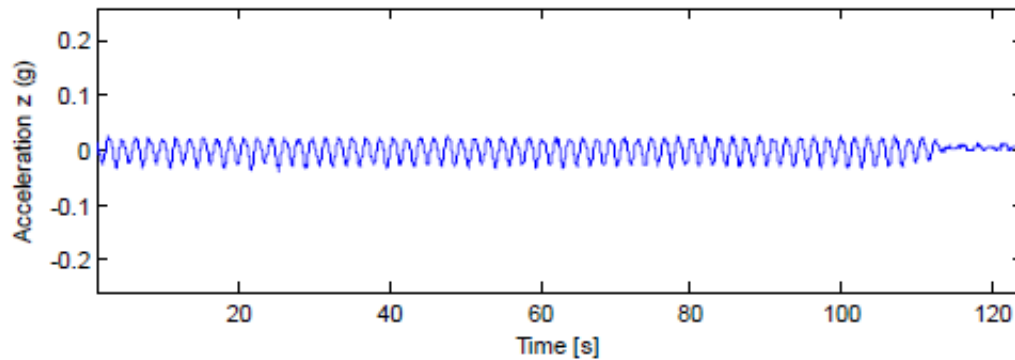


Scale testing: *Wind + waves*

AIRY 15 1.8.csv; H=19.0cm, T=1.8s



AIRY 15 1.8.csv; H=19.0cm, T=1.8s



Scale testing: *Wind + waves*

AIRY TESTS							
Mooring Dir. ¹	Wind dir. [°]	T [s]	H [cm]	Heave max [cm]	Pitch [°]	Roll [°]	Nacelle Max Acc. X [g]
1	83.9	1.2	9.1	0.4	-0.2 ± 1.3	2.5 ± 0.3	0.128
	83.4	1.8	18.5	1.9	-0.2 ± 3.1	2.5 ± 0.7	0.169
	178.6	0.9	7.2	0.2	-3.0 ± 0.6	-0.2 ± 0.7	0.082
	179.0	1.2	9.6	0.5	-3.0 ± 1.2	-0.1 ± 1.0	0.119
	179.0	1.5	14.0	1.5	-3.0 ± 2.4	-0.1 ± 0.9	0.153
	179.1	1.8	18.7	2.2	-3.0 ± 3.2	-0.1 ± 0.6	0.166
2	1.2	1.2	9.3	0.5	2.8 ± 1.2	0.7 ± 1.0	0.109
	1.1	1.5	14.5	1.2	2.8 ± 2.0	0.7 ± 0.9	0.150
	1.1	1.8	18.8	2.0	2.9 ± 3.0	0.6 ± 1.0	0.170
	0.9	2.3	28.5	3.0	2.9 ± 5.2	0.5 ± 1.4	0.183
	25.4	0.9	6.6	0.2	3.0 ± 0.9	0.5 ± 0.8	0.075
	25.6	1.2	9.5	0.5	2.9 ± 1.1	0.5 ± 0.8	0.115
	25.6	1.5	14.1	1.2	2.9 ± 2.0	0.4 ± 1.0	0.157
25.7	1.8	18.7	2.0	2.9 ± 2.9	0.4 ± 1.2	0.172	
IRREGULAR TESTS							
Mooring Dir. ¹	Wind Dir. [°]	T _p [s]	H _s [cm]	Heave max [cm]	Pitch [°]	Roll [°]	Nacelle Max Acc. X [g]
1	84.2	0.9	5.1	0.6	-0.3 ± 1.2	-2.5 ± 0.9	0.156
	179.0	0.9	4.9	0.6	-3.0 ± 0.9	-0.2 ± 1.0	0.159
	179.0	1.8	21.4	3.6	-2.9 ± 5.2	-0.1 ± 1.5	0.399
2	1.4	0.9	5.1	0.7	2.9 ± 1.2	0.5 ± 1.7	0.167
	1.4	1.8	21.2	3.7	2.8 ± 7.2	0.6 ± 1.6	0.363
	25.6	0.9	5.2	0.5	3.0 ± 1.8	0.5 ± 1.9	0.158
	25.5	1.8	15.9	3.7	3.0 ± 6.1	0.4 ± 2.5	0.362

REFINED CONCEPT, after experiments and verification

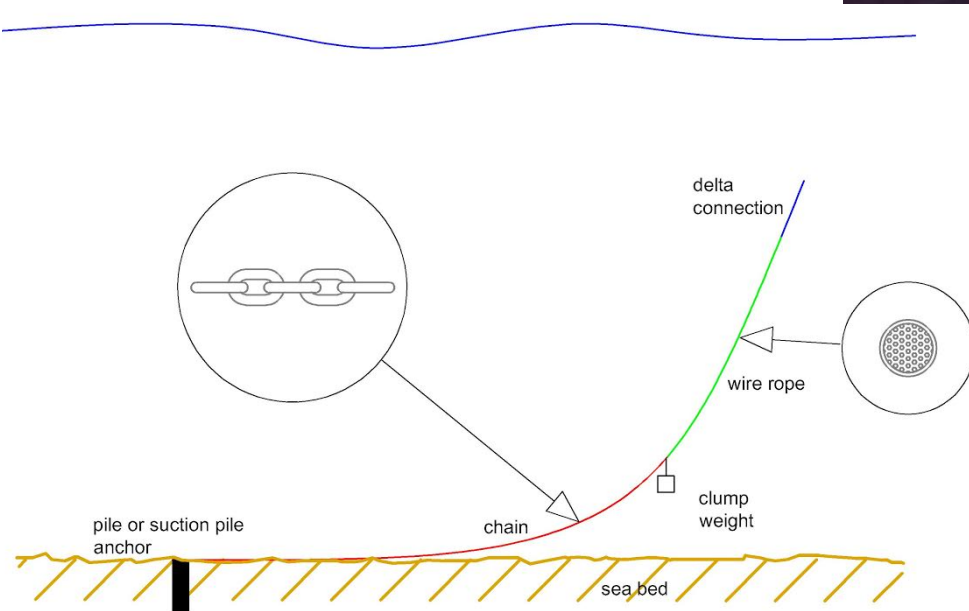
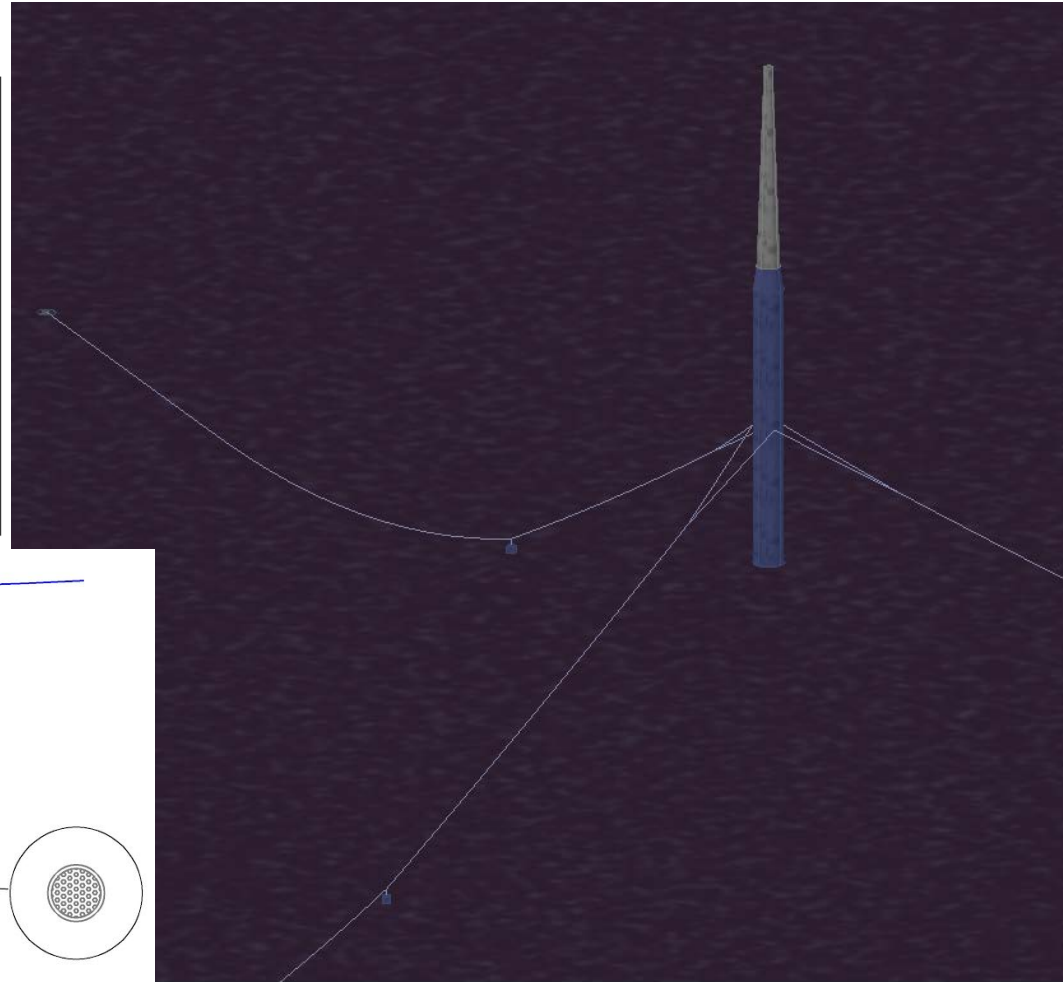
- Experiments show a good behavior: RAO's, free decay, coupled wind and wave (regular and irregular) for the selected cases.
- Detailed simulations detected a need for a larger yaw stiffness for some accidental cases.



- Design of the mooring system has been revised in order to fulfill the required yaw stiffness.
- New system requires the use of suction piles, larger diameter moorings, intermediate weights and delta connection to the platform.

REFINED CONCEPT

Anchor radius [m]	750
Line length [m]	782
Chain length [m]	472
Wire rope length [m]	250
Delta line length [m]	60
Chain mass per unit length [kg/m]	275
Wire rope mass per unit length [kg/m]	67
Clump Weight mass [T]	63



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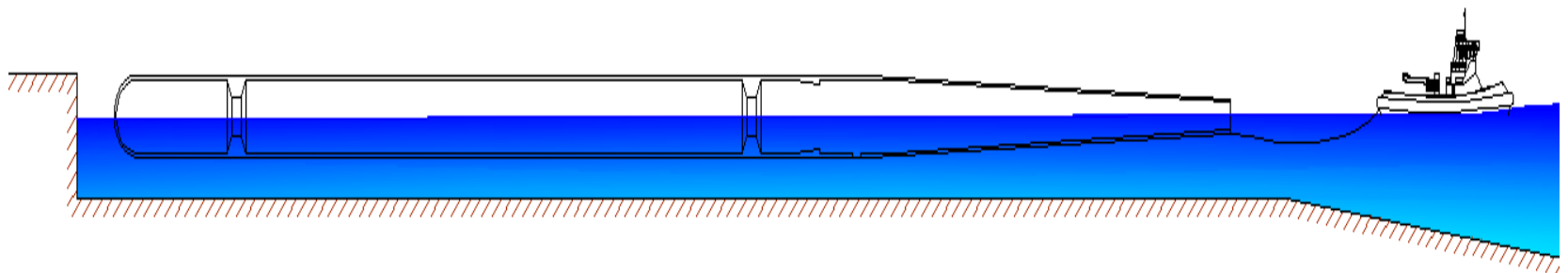
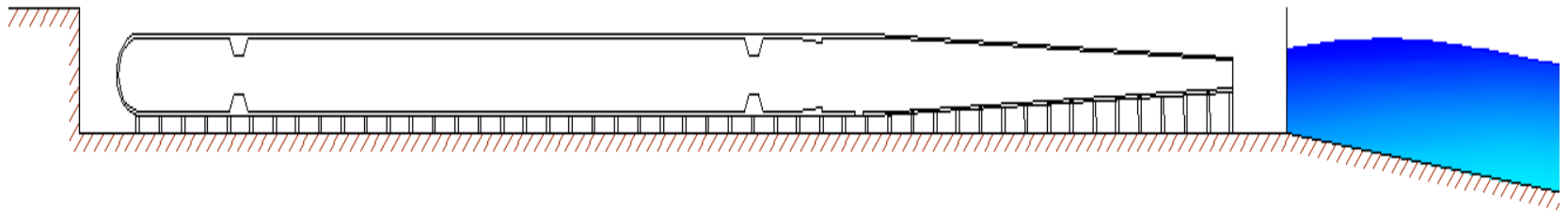
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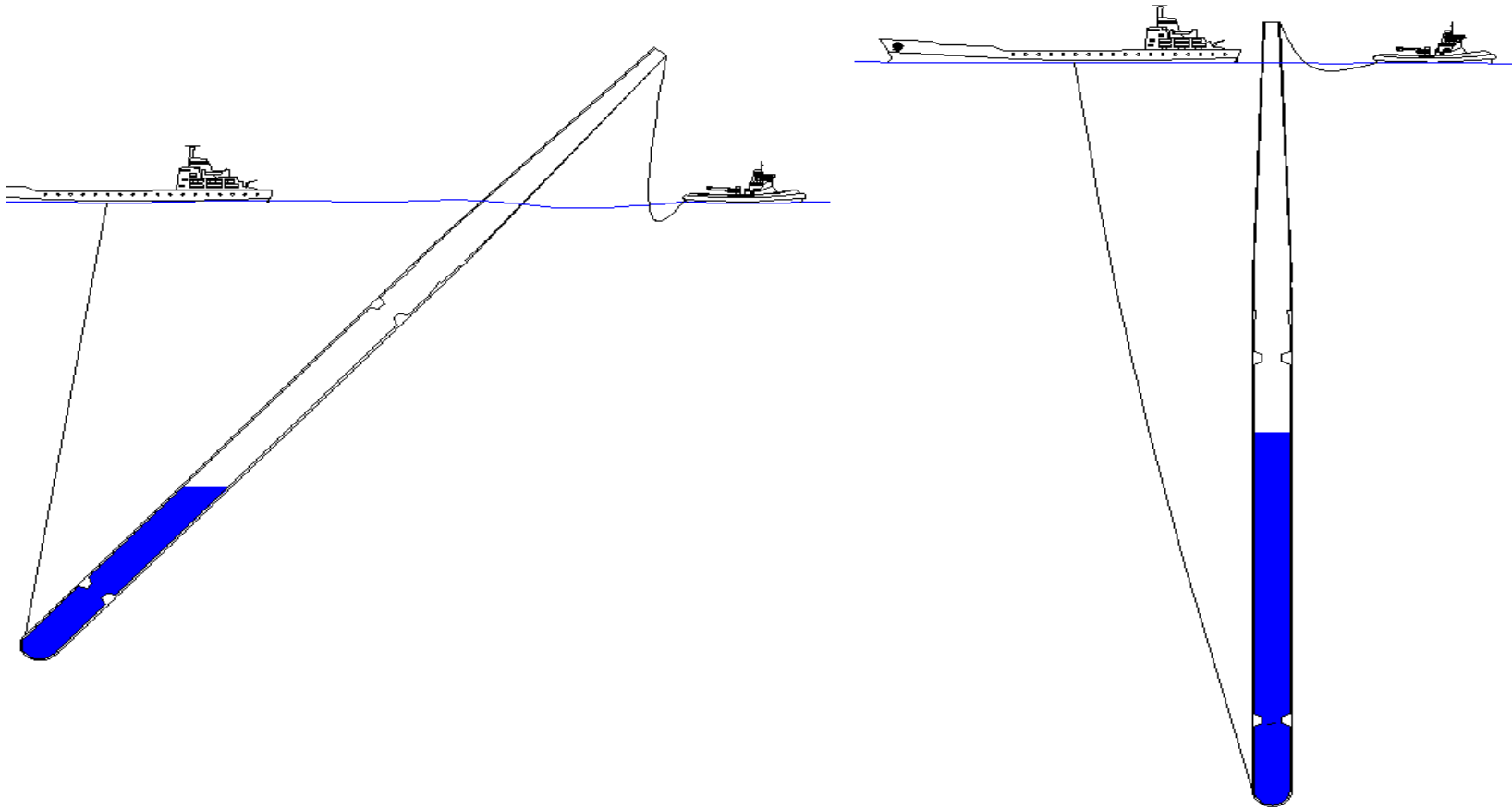
3.- Conclusions

4.- Q&A

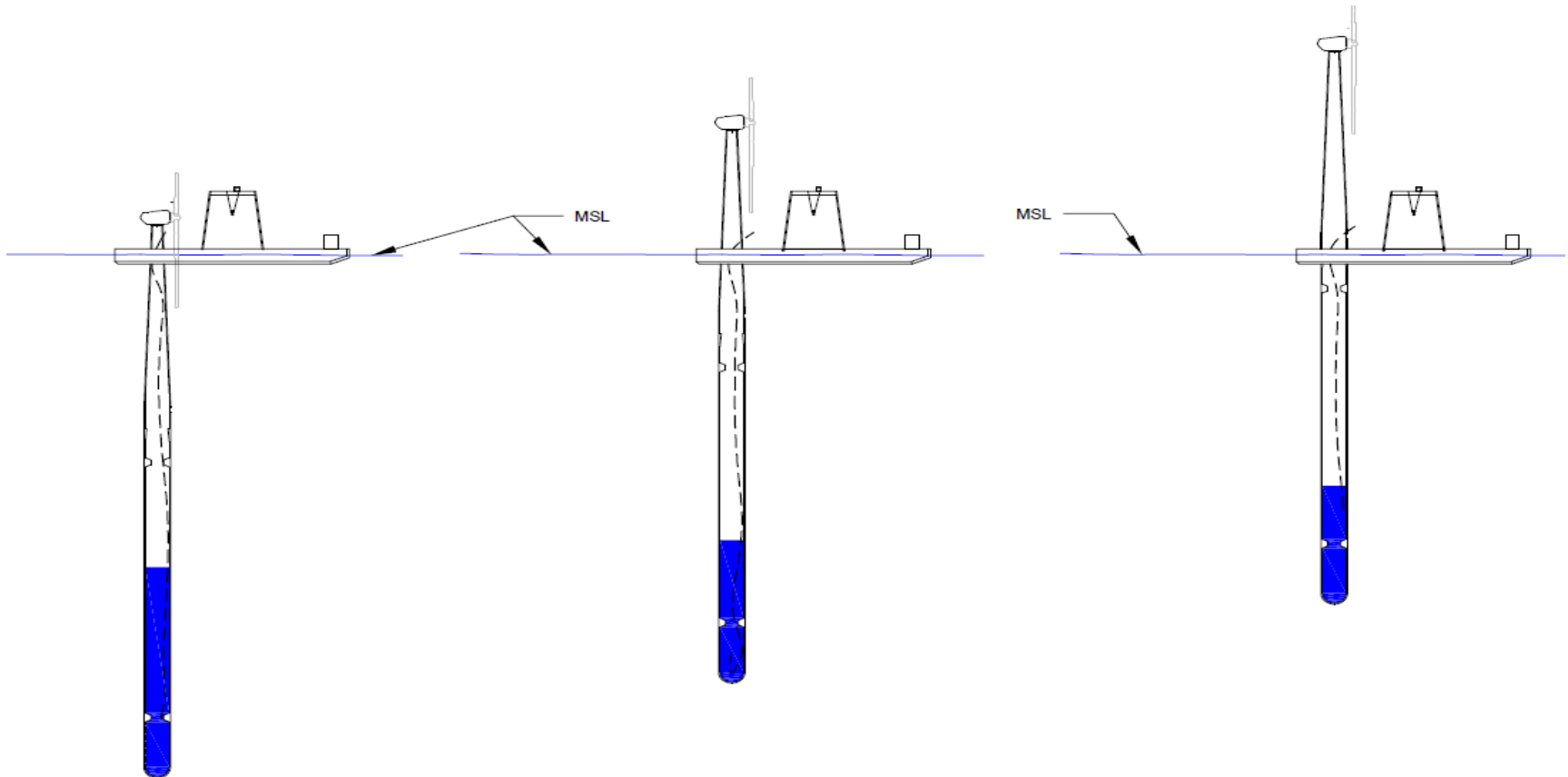
The structure is built horizontally in a dry dock to be towed out to the installation site

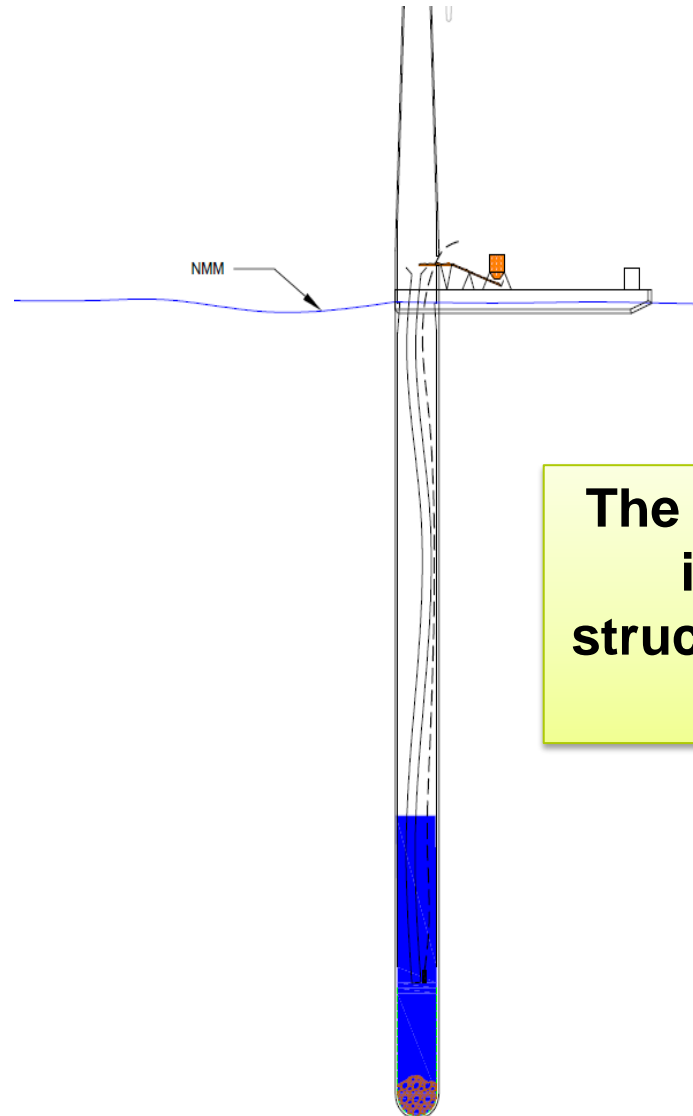


The structure is partially sunk while starts to erect. The erection is controlled by using a cable attached to a boat.



FOWT installed avoiding heavy cranes, being emerged after the installation.





The ballast aggregates are introduced into the structure while the water is pumped out

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4.- Q&A

- The Afosp project has proven the **technical feasibility and viability** of the developed design by experiment and numerical simulations.
- The design was **adjusted and optimized** according to findings from simulations and tests.
- LCOE for Afosp is **25% lower** than LCOE for floating solutions.

•AFOSP solution main **advantages** regarding LCOE:

